## Manual: ${ }^{\circ} 1433$ Installation, connection \& programming

## Rapid insulated Murax shutter



## CS 310 FU Box

 with frequency converter
(Document reserved for installers)

## Contents

Required material ..... p. 2
Installation instructions ..... p. 3
Operator information ..... p. 4
Installation of the axis ..... p. 4
Connection to the box ..... p. 6
Connection to the operator ..... p. 8
Putting into operation ..... p. 8
Language selection ..... p. 9
Setting the limit-switches ..... p. 9
Presentation of the LCD screen ..... p. 10
Table of parameters (factory standard configuration) ..... p. 11
Choose the mode of functioning :

- Pulse operation ..... p. 12
- Automatic operation ..... p. 13
Partial opening ..... p. 13
Safety connections ..... p. 14
Setting the frequency converter ..... p. 15
Presentation of functions ..... p. 16
Fault display and solutions ..... p. 29
In case of operator malfunction ..... p. 31
Mounting the winch on R400 operator (option) ..... p. 33
Mounting the winch on R750 operator (option) ..... p. 34
Emergency operation by crank / winch (option) Detachable section


## Required material

- Lifting equipment
- Clamps
- Spirit level
- Plumb bob
- Tape meter (5m)
- Percussion drill
$-8,10,15$ and 17 mm flat spanners
- 5" hexagonal wrenches
- 10, 15 and 17 mm pipe wrenches
- Screwdriver
- Grease with brush
- Power pliers


## Installation instructions

## 1 <br> WARNING!

To reduce the risks, read the following instructions carefully before installation.
Pay close attention to all markings in the text.
Failure to follow all the elements of this manual in all respects may compromise the proper operation of the system, lead to dangerous situations and in any case void the guarantee of proper operation of the product.

* The device described in this booklet must only be used for the purpose for which it was expressly
designed, namely : Control system for shutter and grille (as defined in standard EN 13241 + A2).
* The entire installation must be carried out in accordance with the state of the art and, in particular, in compliance with the directives:
- 2004/108/EC Electromagnetic Directive
- 2006/95/EC Low Voltage Directive
- 2006/42/EC Machinery Directive and the applicable sections of the corresponding standards in force, including NFC15-100, mainly for the conditions of connection, insulation and protection of persons and equipment.
* All connection operations (wiring, installation of options, etc.) must be carried out by authorized personnel with the power switched off.
* The entire installation must be maintained and kept in good working conditions.
* The materials used must be adapted to the atmospheric conditions of the location.
* If there is any doubt about the safety and/or reliability of the installation of this product, stop the installation and contact us.
* Before performing any cleaning or maintenance work, turn off the power to the unit.
* In the event of failure or malfunction, turn off the power immediately and contact technical support.

Any repairs must be carried out by specialized personnel who must ensure that only original and certified spare parts are used.

* The work carried out is entirely the responsibility of the installer.

We decline all responsibility in case of :

- Electrical installation that does not comply with current standards, especially in the case of an ineffective protective circuit (earthing).
- Unsuitable adjustments made by the customer that may lead to a dangerous situation or destruction of the equipment.
* The installer must ensure that the system is in good working order, including all safety functions before use.
* Keep this manual for future reference.


## Operator information

|  | OPERATOR |  |  |
| :---: | :---: | :---: | :---: |
|  | R400 | R750 | R1250 |
| Output torque (Nm) | 400 | 750 | 1250 |
| Output rotation speed (rpm) at 50 Hz | 24 |  |  |
| Operator speed (rpm) at 50 Hz | 1350 | 1365 | 1400 |
| Operator power (W) | 1700 | 3000 | 4000 |
| Power factor (cosine Phi) of the operator | 0.71 | 0.8 | 0.73 |
| Operating voltage (V) | 400/3 ${ }^{2}$ + N |  |  |
| Power supply frequency (Hz) | 50 |  |  |
| Control circuit voltage (V) | 24 |  |  |
| Nominal motor current (A) | 4,2 | 7 | 10 |
| Max. cycles per hour | 20 |  |  |
| Power cable to be provided on site ( $\mathrm{mm}^{2}$ ) | $5 \times 2,5$ |  |  |
| Fuse protection to be provided on site (A) | 10 |  |  |
| Protection class (IP) | 54 |  |  |
| Temperature range ( ${ }^{\circ} \mathrm{C}$ ) | $-20 /+60$ |  |  |
| Continuous sound pressure level (dB (A)) | $<70$ |  |  |
| Unit weight (Kg) | 32 | 43 | 72 |
| Ø Keyed shaft (mm) | 40 | 50 | 55 |

## Installation of the axis

1- Opposite side to the operator (OO) :

- Attach the winding plate to the wall.
- Attach the 2 brackets provided.


2- Operator side (OS) :

- Disassemble the upper half winding plate.

3- Operator side (OS) : Secure the operator mount to the junction bracket.


Firmly attach the support to the wall with the steel pins and 6 TH M14 screws (pins and screws not provided).


Firmly attach the support to the wall with the steel pins and 10 TH M12 screws (pins and screws not provided).

The weight of the shutter is carried by the winding plate (OS) and the operator support ; therefore the support must be attached to the wall very carefully.

Opposite side to the operator (OO)

4- Installing the shaft :

- Fit the bearing onto the shaft, screw the clamping washer to the end of the shaft with the FHC M8x16 screw with threadlock.
- On the operator side, position the keyed shaft on the lower half-plate.
- On the opposite side, screw the bearing to the plate with the corresponding screws, inserting shims in between them.


5- Installing the operator: Stick it on the keyed shaft.

$\triangle$The axis must be parallel with the header and the keyed shaft must be centered on the plate.

Position it on its support and attach it with 2 bolts M12×45 and 4 washers of 12 (R400/R750) or 2 bolts M14x60 and 4 washers of 14 (R1250).
Reassemble the upper half winding plate and attach it to the wall.


The front plates must remain parallel throughout the entire operation, so use additional supports (not provided).

6- Once the structure is assembled, check:

Opposite side to the operator (OO)


Shoulder up against the bearing

Operator side (OS)


Between the shoulder and the operator

## Connection to the box



Neutral obligatory



External radio (option)


Ensure the power line is protected using an upstream differential circuit-breaker of type B or B+.
Ensure that in close proximity to the operator, there is :

- A thermal protection device for the operator.
- A power cut-off system, which is accessible to the user.


Connect all accessories and safety devices, so that they are recognized by the microprocessor when the unit is switched on.

## Putting into operation

Please note: Unscrew the cover to access terminal X1.
Connection of the box to the mains $400 \mathrm{~V}+\mathrm{N}$ Tri :

(A) Braking resistor.
(B) Brake module.

R1250 operator box

(C) Frequency converter.
(D) Load contactor.

A frequency converter generates continuous leakage currents.
To prevent unintentional tripping of the earth leakage circuit breaker, it is essential to install one, type B or B+, separate for each door.


- Exit INPUT mode by holding down + and - for > 1s


## Setting the limit-switches

## On the LCD screen



- Select the ADJUSTMENT mode, by holding down the P button $\longrightarrow$


## ADJUSTMENT STANDBY

## - Setting the top limit-switch :

Move the door to the required OPEN limit-switch, by pressing the + button.

| If the shutter does not go up, reverse the direction of operator rotation, <br> pressing buttons + and - for > 5 seconds simultaneously. <br> The screen displays : OS LEFT ROT. <br> (Any saved limit-switch positions are deleted). <br> Reset the limit switches. |
| :--- |

Record the limit switch OPEN, first holding down the button $P$ and while holding $P$, hold + until display

| ADJUSTMENT |  |
| :--- | :--- |
| RECORD UP |  |

## - Setting the bottom limit-switch position:

Move the door to the required CLOSE limit-switch position, by pressing the - button.
Memorize the limit switch CLOSE, first holding the button P and while holding P , hold - until display

ADJUSTMENT

## - The limit-switches have now been set.

- Exit the ADJUSTMENT mode, by holding down the $P$ until AUTOMATIC mode is selected.

Please note : For a more precise setting of the limit switches, see parameters ADJUST. OPEN and ADJUST. CLOSE

A - Operating mode / Diagnostic info
B - Parameter / Diagnostic info
C - Button (+)
D - Button (-)
E-Button (P)
F - Value / Status
G - Value / Status
H - Jumper


Selecting a mode on the LCD screen (A) :
By holding down the P button, you can select the following modes :
1-AUTOMATIC 2-ADJUSTMENT 3-INPUT 4-DIAGNOSTIC
Please note : If the H jumper is removed, the (+), (-) and (P) buttons will not work. The screen display will continue to work.

Description of mode 1 : AUTOMATIC (AUTOHOLD = MOD1)
The door will operate in this mode.
On screen : - The operating mode is displayed (e.g. AUTOMATIC).

- The shutter status or potential faults are displayed (e.g. STANDBY).

MANUAL (AUTOHOLD = MOD2/3/4/5/6)
The door will operate in this mode.

Description of mode 2 : ADJUSTMENT = Setting the limit-switches.

4
In ADJUSTMENT mode, there is no stop position because the limit-switches are reached. Overrunning the limit-switches may damage the door.

On screen : - The limit-switch value is displayed.
Description of mode 3: INPUT = Modification of different parameters for shutter operation of the curtain.

On screen : - Display the selected parameter.

- The set value / status is displayed.

Description of mode 4 : DIAGNOSTIC = The status of the controls and safety devices is displayed.
On screen : - Display of the elements to be checked.

- The checked component value is displayed.


## Table of parameters (factory standard configuration)



OFF: Access to essential parameters
ON: Access to all parameters

| ENGLISH |  |
| :---: | :---: |
| ADJUST. OPEN | 0 |
| ADJUST. CLOSE | 0 |
| P.INT. OPEN | A |
| P.INT. CLOSE | A |
| OPENING TIME | OFF |
| WARNING. START | OFF |
| WARNING | OFF |
| AUTO CLOSE | MOD1 |
| CLOSE RAP | OFF |
| RELAY 1 | MOD6 |
| RELAY 2 | MOD7 |
| RELAY 3 | MOD1 |
| RELAY 4 | MOD14 |
| LIGHT STANDBY | MOD1 |
| SKS | A |
| T ODC | MOD2 |
| DW-POINT | 20 |
| SKS FUNC. | MOD1 |
| SKS INV | MOD1 |
| REVERSE OFF | 50 |
| PHOTO CELL. 1 | A |
| P/C FUNC. 1 | MOD1 |
| P/C FUNC. 2 | MOD1 |
| CEL POINT | A |
| PULSE | MOD1 |
| INPUT 1 | MOD1 |
| INPUT 2 | A |
| SKS3 | MOD1 |
| SKS4 | MOD1 |
| D OF MOV | A |
| T. INVERSE | 300 |
| END OF C. | A |
| AUTOHOLD | MOD1 |
| FORCE | 10 |
| RESET MSBUS | OFF |
| RESTARTING | OFF |
| FACTORY | MOD8 |
| RESET | OFF |
| CODE PN 2 | 1111 |
| SERVICE | OFF |
| CONVERT. | MOD2 |
| P.BRAKE OPEN | -250 |
| P.BRAKE CLOSE | 250 |
| P.BRAKE FE2 | A |
| SPEED OPEN. | 50 |
| SPEED CLOSE. | 50 |
| SPEED MX CLOSE | 50 |
| OPEN SLOW | 25 |
| CLOSE SLOW | 25 |
| ACCEL. OPEN. | 2,0 |
| ACCEL. CLOSE. | 2,0 |
| TEMPOR. OPEN | 2,0 |
| TEMPOR. CLOSE. | 2,0 |
| ACCEL. MX | 2,0 |
| TEMPOR. MX | 2,0 |
| ACCEL. SKS | 0,5 |
| TEMPOR. SKS | 0,1 |
| ACCEL. WGI | 0,5 |
| TEMPOR. WGI | 0,5 |
| TEMPOR. STOP | 0,5 |
| RESET CONV. | OFF |
| OPERATOR V | 400 |
| OPERATOR I |  |
| OPERATOR P |  |
| OPERATOR PHI |  |
| OPERATOR HZ | 50 |
| OPERATOR T/M |  |
| OPERATOR HZ MIN | 10 |
| OPERATOR HZ MAX | 87 |
| T BRAKE | 50 |
| EXPERT MENU | OFF |
| BOOST CONT. | 50 |
| BOOST ACCEL. | 50 |
| BOOST START | 0 |

Scroll menu forward

Scroll menu backwards Press -

Select parameter
Press $P$
Increase value
Press +
Decrease value
Press -
Save value
Press P

Exit mode INPUT
Hold down + and - for > 1s

| Operator |  |  |
| :---: | :---: | :---: |
| R400 | R750 | R1250 |
| 400 |  |  |
| 4.2 | 7 | 10 |
| 1700 | 3000 | 4000 |
| 0.71 | 0.8 | 0.73 |
| 50 |  |  |
| 1350 | 1365 | 1400 |

Set the limit-switches before selecting the operating mode.
The fixed controls must be installed within sight of the door but away from any moving parts and at a height of at least 1.5 m from the floor.

Use one switch for a single operator. It is completely prohibited to control several operators with a single monopolar switch.

## Pulse operation <br> Up/Down Pulse

1- Connection of the controls:


Please note : If operating with the remote control, refer to the corresponding receiver box manual.
2-Check :

| OPENING TIME | OFF | If $>0:$ automatic operation |
| :--- | :--- | :--- |

3- Parameters to be modified for pulse operation :

| WARNING START | 3 | Advance notice before opening and closing |
| :--- | ---: | :--- |
| SKS | MOD1 | Opto-electronic safety edge |
| PHOTO CELL. 1 | MOD2 | Photo. cells Contact NC |
| END OF C. | MOD1 | Digital limit switch |
| AUTOMATED | MOD1 | Pulse/automatic operation |

# Automatic operation <br> Pulse ascent and automatic re-closing 

The timed re-closing is integrated into the automatic operating mode (no manual control), cf : NF EN 12453 - NF EN 13 241-1


## Ensure that the mandatory protection levels are in place for automatic operation



1- Connection of the controls :


Please note : If operating with the remote control, refer to the corresponding receiver box manual.
2- Paramters to be modified for automatic operation :

| OPENING TIME | 10 | Open shutter delay |
| :--- | ---: | :--- |
| WARNING START | 3 | Advance notice before opening and closing |
| SKS | MOD1 | Opto-electronic safety edge |
| PHOTO CELL. 1 | MOD2 | Photo. cells NC contact |
| PULSE | MOD2 | Opening priority |
| END OF C. | MOD1 | Digital limit switch |
| AUTOHOLD | MOD1 | Pulse/automatic operation |

## Partial opening (see input 1 functions)



CS 310 Box terminal block

Partial opening setting :

- Move the door to the desired position using the buttons on the front of the box.
- Press on P until ENTRY mode.
- Press + and - for $>2 \mathrm{~s}$, to enter the mode INPUT.
- Press on + or - until display of P.INT. OPEN (displayed value is A).
- Press P to validate the door position.
- Press P again to save the value.
- Exit INPUT mode.


## Safety connections

## Bottom safety edge with auto-test

Please note:
If the safety edge is faulty, the operating mode is switched
unction box to be attached to the end-slat


## Bottom cells



## Orange flashing lights (option)

230V - MAXI 4 A


CS 300 Box terminal block

Illumination lights (option)
230V - MAXI 4 A


CS 310 Box terminal block

## Setting the frequency converter

## Opening

1
Opening:
SPEED OPEN. $\leq 75$ Hertz


Closure

Closing :
SPEED CLOSE = 25 Hertz


| TEMPOR. CLOSE. | 2.0 |
| :--- | :--- |

Visual on the parameter table

| P.BRAKE OPEN | $-125 /-250$ |
| :--- | ---: |
| $\ldots$ |  |
| SPEED OPEN. | $\leq 75$ |
| $\ldots$ | 25 |
| SLOW OPEN. |  |
| $\ldots$ | 2,0 |
| ACCEL. OPEN. |  |
| $\ldots$ | 2,0 |
| TEMPOR. OPEN. |  |

Please note : The range of P.BRAKE OPEN must be between -125 and -250

| P.BRAKE CLOSE | $250 / 125$ |
| :--- | ---: |
| $\ldots$ |  |
| SPEED CLOSE | $=25$ |
| $\ldots$ | 25 |
| SLOW CLOSE |  |
| $\ldots$ | 2,0 |
| ACCEL. CLOSE |  |
| $\ldots$ | 2,0 |
| TEMPOR. CLOSE |  |

Please note : The range of P.BRAKE CLOSE must be between 250 and 125

## Presentation of functions

## AUTOMATIC mode :

| Display |  | Description |
| :--- | :--- | :--- |
| AUTOMATIC TEACH | Movement time is learned automatically |  |
| AUTOMATIC OPEN | The door moves to the top limit-switch position |  |
| AUTOMATIC CLOSE | The door moves to the bottom limit-switch position |  |
| AUTOMATIC STANDBY | O | The door is in the top limit-switch position |
| AUTOMATIC STANDBY | U | The door is in partial opening position (parameter "P.INT. OPEN") |
| AUTOMATIC STANDBY | U The door is in the bottom limit-switch position |  |
| AUTOMATIC STANDBY | The door is in the partially closed position (parameter "P.INT. CLOSE") |  |
| AUTOMATIC STANDBY | Door is in the reverse motion disabling range (SKS) |  |
| AUTOMATIC STANDBY | A signal is emitted continuously : Unauthorized control device or programmable input <br> (defective component to be replaced). <br> Exception: The signal comes from the plug-in timer or is output via programmable input 1, <br> if this is defined as a timer function (MOD4) or fire alarm function (MOD5 to 9, 13). |  |
| AUTOMATIC PERMANENT SIGNAL |  | The door collision sensor has been activated. <br> (connection on strip X4, between 9 and 10, programmable input 1, MOD18) <br> A vehicle (fork-lift truck) has probably hit the closed door. |
| AUTOMATIC CRASH SENSOR |  |  |

Please note : If the "AUTOHOLD" parameter is set on MOD2, 3, 4, 5 or 6 in INPUT mode, the screen display will change from AUTOMATIC to MANUAL.

| Display | Description |
| :--- | :--- |
| MANUAL <br> MANUAL LIFTING | The door moves to the top limit-switch position |
| MANUAL <br> MANUAL DESCENT | The door moves to the bottom limit-switch position |
| MANUAL <br> STANDBY | The door is in the intermediate position |

## INPUT mode :

| Function | Description | Available settings | Factory settings |
| :---: | :---: | :---: | :---: |
| ENGLISH | Selecting a language | DEUTSCH <br> ENGLISH <br> FRANCAIS <br> NEDERLANDS <br> DANSK <br> ESPANOL <br> POLSKI <br> CESKY <br> ITALIANO <br> SUOMI <br> SVENSKA <br> TÜRKÇE <br> NORSK <br> MAGYARUL | DEUTSCH |
| ADJUST. OPEN. | Precise adjustment of the high limit switch in relation to the saved high limit switch (LS OPEN). <br> Visible only in systems with electronic limit switch. | -250 to 250 | 0 |
| ADJUST. CLOSE | Precise adjustment of the low limit switch in relation to the saved low limit switch (LS CLOSE). <br> Visible only in systems with electronic limit switch. | -250 to 250 | 0 |


| Function | Description | Available settings | Factory settings |
| :---: | :---: | :---: | :---: |
| P.INT. OPEN | Adjustment of the partial opening in relation to the saved high limit switch (negative value display). <br> Visible only with electronic limit switches. <br> - Automatic teach-in of the position, see chapter : Partial opening. | $\begin{aligned} & \text { A (learning) } \\ & -1=\text { LS CLOSE } \end{aligned}$ | A |
| P.INT. CLOSE | Adjustment of the partial opening in relation to the saved bottom limit switch (positive value display). <br> Visible only with electronic limit switches. <br> - Automatic teach-in of the position. | $\begin{aligned} & \text { A (learning) } \\ & 1=\text { LS OPEN } \end{aligned}$ | A |
| OPENING TIME | After opening, the door moves automatically to CLOSE after the set values have elapsed. <br> Comment : By pressing the CLOSE button, while opening, <br> the closure is triggered immediately. <br> By pressing the OPEN or STOP button during opening, the time starts from zero. If the safety edge interrupts an automatic closing, the opening time is multiplied by 2 and after 3 attempts, the automatic closing is cancelled. | $\begin{aligned} & \text { OFF = Closing } \\ & \text { auto } \\ & \text { disabled } \end{aligned} 1 \text { to } 3600 \text { seconds }$ | OFF |
| START WARNING | A start warning is given before each trip. | $\begin{aligned} & \text { OFF = OFF } \\ & 1-10 \text { seconds } \end{aligned}$ | OFF |
| WARNING | The warning time is activated before an automatic closing or closing by pulse operation. <br> Comment : The time is added to the start warning. | $\begin{aligned} & \text { OFF = OFF } \\ & 1-300 \text { seconds } \end{aligned}$ | OFF |
| CLOSED. AUTO | Automatic closing after the elapsed time (time delay). <br> MOD1 : AUTO CLOSE from the high limit switch. <br> MOD2 : AUTO CLOSE from partial opening. <br> MOD3 : AUTO CLOSE from the high limit switch and partial opening. <br> MOD4 : CLOSED. AUTO from all door positions. | MOD1 to MOD4 | MOD1 |
| CLOSED. RAP | Premature closure once through the cells. <br> Condition : Connection of the cells at the height of the passage and setting of an opening time $>$ to 0 seconds. <br> MOD2 : The opening time is cancelled after passing the cells (the door closes immediately). <br> MOD3 : The opening time is cancelled after the cells have been switched off for at least 2 seconds (no detection of persons). <br> MOD4 : Same as MOD2, but the cells are without function during the opening of the door. | OFF = The opening time functions normally <br> MOD2 to MOD4 | OFF |
| RELAY 1 | A relay mode from 1 to 13,17 to 19,21 to 43 and 60 to 62 can be assigned to each of the 4 relays. <br> In addition, relay 4 can also be programmed from 14 to 16. <br> MOD1 : (Red light 1) Warning - flashing, moving door - on* <br> MOD2 : (Red light 2) Warning - flashing, moving door - flashing* <br> MOD3 : (Red light 3) Warning - on, moving door - on* <br> MOD4 : Pulse signal in inside opening command <br> MOD5 : Fault signal <br> MOD6 : Top limit-switch <br> MOD7 : Bottom limit-switch | MOD1 to MOD13 MOD17 to MOD19 MOD21 to MOD43 MOD60 to MOD62 | MOD6 |
| RELAY 2 | MOD8 : Top limit-switch denied <br> MOD9 : Bottom limit switch denied <br> MOD10 : Partial opening position <br> MOD11 : Partial closure position <br> MOD12 : Partial closing position up to the low limit switch <br> MOD13 : Magnetic latch function <br> MOD14 : Brake <br> MOD15 : Reverse brake <br> MOD16 : Brake activated at the upper limit switch <br> MOD17 : Safety edge activated or test error <br> MOD18 : (Red light 4) Warning - flashing, moving door - off | MOD1 to MOD13 MOD17 to MOD19 MOD21 to MOD43 MOD60 to MOD62 | MOD7 |
| RELAY 3 | MOD19 : Partial opening position up to top limit-switch <br> MOD21 : Anti-lift safety device test before opening (additional module required) <br> MOD22 : Activation of radio transmission system 1 and 3 or light barrier test <br> MOD23 : (Green light) Top limit switch - on, <br> Warning - off, <br> Door moving - off* <br> MOD24 : Condenser activation for operator 230V 1Ph | MOD1 to MOD13 MOD17 to MOD19 MOD21 to MOD43 MOD60 to MOD62 | MOD1 |


| Function | Description | Available settings | Factory settings |
| :---: | :---: | :---: | :---: |
| RELAY 4 | MOD25 : Yard light function 2 minutes after the opening command (also indirectly by pulse) <br> MOD26 : Radio transmission system activation 2 <br> MOD27 : Pulse signal after having reached the top limit-switch <br> MOD28 : General relay off <br> MOD29 : The door opens <br> MOD30 : The door closes <br> MOD31 : Continuous signal when the set maintenance interval is reached <br> MOD32 : Battery operation <br> MOD33 : No operation on battery <br> MOD34 : BMA signal (fire alarm system) <br> MOD35 : Cells in operation <br> MOD36 : Wicket door locking cylinder <br> MOD37 : Test stop signal of radio transmission system 1 and 3 <br> MOD38 : Test light barrier 2 (input 2) <br> MOD39 : LED Error <br> MOD40 : Pulse signal in exterior opening command <br> MOD41 : Test radio transmission system 4 in opening direction <br> MOD43 : Motorization in motion <br> MOD60 : (Red exterior light) Warning - flashing, door in motion - on <br> MOD61 : (Red exterior light) Warning - flashing, door in motion - flashing <br> MOD62 : (Outside green light) Top limit switch - on, Warning/door moving - off <br> * When reverse traffic control is activated : INTERIOR LIGHT. | MOD1 to MOD19 MOD21 to MOD43 MOD60 to MOD62 | MOD14 |
| LIGHT STANDBY | Light control <br> MOD1 : Off at standby <br> MOD2 : On at standby <br> MOD3 : Switches off at rest after 5 minutes | MOD1 to MOD3 | MOD1 |
| SKS | MOD1 : OSE (Opto-electronic sensor) <br> MOD2 : $8 \mathrm{k} \Omega$ (electric safety edge) <br> MOD3 : ODC (pneumatic safety edge) as NF with test <br> MOD4 : OSE light barrier without test <br> MOD5 : PNP light barrier with test <br> MOD6 : PNP light barrier without test | A (auto-adaptive) MOD1 to MOD6 | A |
| T ODC | Activation and deactivation of the test function for the connected pneumatic safety edge. <br> Appears when setting the parameters SKS = MOD3. <br> MOD1 : Test OFF <br> MOD2 : Test ON | MOD1 to MOD2 | MOD2 |
| DW POINT | Point where the connected pneumatic safety edge (X4 between 5 and 6 ) is tested. Appears when setting the parameters SKS = MOD3. <br> Adjustment in increments (AWG only) from the lower end deactivation point. | 0 to 1000 | 20 |
| SKS FUNC. | MOD1 : Stop + Reversal <br> MOD2 : Stop + Reversal for 2 seconds | MOD1 to MOD2 | MOD1 |
| SKS INV | MOD1 : Stop + Reversal, between high limit switch and reversal point Stop, between reversal point and low limit switch. <br> $\rightarrow$ For vertically closing doors. <br> MOD2 : Stop+reversal, between high limit switch and reversal point No action, between reversal point and low limit switch. <br> $\rightarrow$ For vertically closing doors with advanced position sensors. <br> MOD3 : Stop + Reversal, between high and low limit switches. <br> $\rightarrow$ For horizontally closing doors and devices with mechanical limit switches without prelimit switches. <br> Comment : For systems with mechanical limit switches, the additional low limit switch serves as a changeover point. | MOD1 to MOD3 | MOD1 |
| INVERSE OFF | Inversion point. Point where the shutter reversal is disabled (SKS). Appears on systems with electronic limit switches (AWG). Adjustment in increments, starting from the lowest final switch-off point. For systems with mechanical limit switches, the additional low limit switch serves as a changeover point. | A (auto-adaptative) 1 to 1000 | 50 |
| PHOTO CELL. 1 | (Photoelectric) cells 1, mounted in the shutter passage area (connection to X 4 between 1 and 4). <br> MOD1 : MFZ two-wire system <br> MOD2 : Contact NC/NPN <br> MOD3 : PNP | A (auto-adaptative) MOD1 to MOD3 | A |


| Function | Description | Available settings | Factory settings |
| :---: | :---: | :---: | :---: |
| P/C FUNC. 1 | Operation of cell 1, in the shutter area. <br> Shutter Movements CLOSE <br> Shutter Movements OPEN <br> MOD1 : Stop + Reversal <br> No action <br> MOD2 : Stop + Reversal for 2s <br> No action <br> MOD3 : Stop <br> No action <br> MOD4 : Stop <br> Stop <br> MOD5 : Stop + Reversal <br> No person identification <br> MOD6 : No action <br> Stop + Reversal <br> MOD7 : No action <br> Stop + Reversal for 2s <br> MOD8 : No action <br> Stop <br> MOD9 : No person ID <br> Stop + Reversal | MOD1 to MOD9 | MOD1 |
| P/C FUNC. 2 | Operation of cell 2 , in the shutter area. Appears when parameters INPUT 1 = MOD15 are set. Connection only as NC contact to programmable input 1 (X4 between 9 and 10). The modes that can be selected are identical to those of the P/C FUNC function. 1. | MOD1 to MOD9 | MOD1 |
| CEL POINT | Cells 1 (X4 between 1 and 4 ) are not evaluated between the low limit switch and the CEL point. <br> djustment in increments, starting from the lowest final switch-off point. <br> Appears on systems with electronic limit switches. | A (auto-adaptative) 1 to LS OPEN | A |
| PULSE | Function to be assigned to the pulse button ( X 3 between 7 and 8). <br> MOD1 : Open - Stop - Close - Stop (sequential control) <br> MOD2 : Only opening, inactive in opening movement stop and opening during closing movement <br> MOD3 : Only opening, stop during movement <br> MOD4 : Only opening, inactive during movement <br> MOD5 : Opening, closing from the upper limit switch | MOD1 to MOD5 | MOD1 |
| INPUT 1 | Function to be assigned to input 1 (X4 between 9 and 10) <br> MOD1 : Partial open button <br> MOD2 : Switch OPEN PART <br> MOD3 : AUTO CLOSE switch <br> MOD4 : External TIMER (continuous OPERATION) <br> MOD5 : Switch BMA 3 (partial opening) NO <br> MOD6 : Switch BMA 1 (emergency closing) NO <br> MOD7 : Switch BMA 1 (emergency closing) NO <br> MOD8 : Switch BMA 2 (emergency opening) NO <br> MOD9 : Switch BMA 2 (emergency opening) NO <br> MOD10 : Ventilation function button (partial closure) NO <br> MOD11 : Automatic close button <br> MOD12 : Laser scanner (special solution) <br> MOD13 : Switch BMA 3 (partial opening) NC <br> MOD14 : Wicket door lock <br> MOD15 : Photocells 2 NC <br> MOD16 : Warning switch <br> MOD17 : Pulse button <br> MOD18 : NC collision sensor <br> MOD30 : Internal opening button <br> MOD31 : External opening button <br> MOD32 : Close button (only active if safety edge and cell 1 are working No function in hold to run mode) | MOD1 to MOD18 MOD30 to MOD32 | MOD1 |
| INPUT 2 (SKS2) | Function to be assigned to input 2 ( X 4 between 11 and 12) <br> OFF : Inactive <br> MOD2 : Wicket door switch $8.2 \mathrm{~K} \Omega$, off in case of discrepancy <br> MOD3 : Electric safety edge $8.2 \mathrm{~K} \Omega$, active in opening, stopping and reversing on activation <br> MOD4 : Electric safety edge $8.2 \mathrm{~K} \Omega$, active in opening, stopping and reversing for 2 s when activated <br> MOD5 : Battery operation <br> MOD6 : Motion sensor radar (special solution) <br> MOD7 : Light barrier 2 (PNP) <br> Please note : During 1st commissioning and after a Reset, input 2 is set to $A$ (auto-adaptative). If no connected component is recognized, the input is automatically deactivated. OFF appears on the display and the entry must be activated manually. | A (auto-adaptative) OFF MOD2 to MOD7 | MOD1 |


| Function | Description | Available settings | Factory settings |
| :---: | :---: | :---: | :---: |
| SKS3 | Setting of channel 1, pluggable signal transmission system (X20) <br> OFF : Inactive <br> MOD2 : Activated as safety edge in closing <br> MOD3 : Activated as safety edge in opening <br> MOD4 : Activated as a safety device (internal circuit) | OFF <br> MOD2 to MOD4 | OFF |
| SKS4 | Setting of channel 2, pluggable signal transmission system (X20) <br> The modes that can be selected are identical to those of the SKS3 function. | OFF <br> MOD2 to MOD4 | OFF |
| D OF MOV | Checking the maximum opening and closing time. <br> The duration of the door movement is automatically programmed during the teach-in run. <br> If there is a discrepancy of $20 \%$ (in both directions), a movement time error is displayed on the screen. <br> It is possible to change the movement time manually after the automatic learning process. | A (auto-adaptative) OFF <br> 1 to 300 seconds | A |
| T. INVERSE | Operator stop time for each voluntary change of direction. <br> The reversal time if the safety edge is activated during the closing movement is $1 / 4$ of the set time. | 100 to 5000 milliseconds | 300 milliseconds |
| END OF C. | Choice of limit-switches to be evaluated. <br> MOD1 : Encoder (AWG) <br> MOD2 : Mechanical Limit Switch (MLS) <br> MOD3 : No function <br> MOD4 : Frequency converter operation <br> MOD5 : Encoder (AWG) + Low mechanical limit switch (NC) for standard installation <br> MOD6 : Encoder (AWG) + Low mechanical limit switch (NC) in case of special mounting with left rotating field <br> Please note : MOD5 and MOD6 (optional) : Additional external mechanical limit switch. | A (auto-adaptative) MOD1 to MOD6 | A |
| AUTOHOLD | Choice between pulse mode or manual mode, with and without evaluation of the safety edge (SKS) and cell system (LS). <br> MOD1 : Pulse mode (open/close) with SKS and LS <br> MOD2 : Manual mode (open/close) with SKS and LS <br> MOD3 : Manual mode (closing) with SKS and LS <br> MOD4 : Manual mode (opening) with SKS and LS <br> MOD5 : Manual mode (open/close) without SKS and LS <br> MOD6 : Manual mode (closing) without SKS and LS | MOD1 to MOD6 | MOD1 |
| FORCE | Automatic force control (rotational speed) | $\begin{aligned} & \text { OFF } \\ & 1 \text { to } 999 \end{aligned}$ | 10 |
| RESET MSBUS | All assigned MSBUS addresses are reset. After restarting the box, all connected MSBUS devices are re-addressed. Please refer to the user manual of the MSBUS device for more information. | $\begin{aligned} & \text { ON } \\ & \text { OFF } \end{aligned}$ | OFF |
| RESTARTING | The box is restarted when a function is activated. | $\begin{aligned} & \text { ON } \\ & \text { OFF } \end{aligned}$ | OFF |
| FACTORY SETTINGS | The choice of parameters must be reset by a RESET. <br> MOD5 : MTZ S $\rightarrow$ Drive unit in hold to run operation <br> MOD6 : MTZ FU $\rightarrow$ MDF-U operation series (integrated ASI) <br> MOD7 : MTZ $S \rightarrow$ STAW operation series with increased running time <br> MOD8 : MTZ FU $\rightarrow$ SA operation series with brake <br> MOD9 : MTZ FU $\rightarrow$ STA operation series <br> MOD14 : MTZ FU $\rightarrow$ MTZ 05 operation series (400V) <br> MOD99 : MTZ S $\rightarrow$ Standard <br> MOD10 to MOD98 : Individual settings | MOD5 to MOD14 MOD10 to MOD98 MOD99 | MOD8 |
| RESET | Reset the parameters of the box to the factory preset parameters. <br> MOD2 : Reset the parameters of the box to the factory preset parameters <br> MOD3 : Partial Reset 2 (everything except limit switches and recognized limit switch system) <br> MOD4 : Total Reset (everything is reset to factory settings) | OFF <br> MOD2 to MOD4 | OFF |


| Function | Description | Available settings | Factory settings |
| :---: | :---: | :---: | :---: |
| CODE PN 2 | Entry and selection of a PN code for maintenance programming. After entering the code, the 2nd programming level opens: <br> A maintenance can be entered in the SERVICE parameter. <br> The 2nd input level turns off after power off or automatically after 10 minutes. <br> Please note : A modification of the PN code can only be made in the 2nd programming level. | 0 to 9999 | 1111 |
| SERVICE | OFF : Maintenance display inactive <br> Set a maintenance interval. <br> After the set number of cycles has elapsed, a maintenance message (LED / LCD) is issued. <br> If a relay output is programmed with MOD31, the relevant relay switches on (continuous signal). <br> Appears after activation of the 2nd input level on the parameters CODE PN 2. | OFF <br> 0 to 9999 | OFF |
| CONVERT. | Activates or deactivates a connected frequency converter. <br> By connecting a frequency converter to the X18 interface, the box is converted to CS 310 FU. <br> MOD1 : Mode without frequency converter (FU) <br> MOD2 : Mode with frequency converter (FU) <br> MOD3 : Mode with FU (actual ramp times) | MOD1 to MOD3 | MOD2 |
| P.BRAKE OPEN* | Sets a negative value before the high limit switch ; Range during which the operator passes at reduced speed (OPEN TEMPOR.) Valid only for the opening direction. | -999 to 0 | -250 |
| $\begin{aligned} & \text { P.BRAKE } \\ & \text { CLOSE* } \end{aligned}$ | Sets a positive value before the low limit switch ; <br> Range during which the operator switches to reduced speed (CLOSE SLOW) Valid only for the closing direction. | 0 to 999 | 250 |
| $\begin{aligned} & \text { P.BRAKE } \\ & \text { FE2* } \end{aligned}$ | Sets a positive value before the low limit switch ; <br> Range during which the operator passes at reduced speed (TEMPOR. MX) If the limit switches are subsequently modified (example: Fine adjustment), the P.BRAKE FE2 will be deactivated (display : A), so it will be necessary to reprogram it. <br> Valid only for the closing direction. | 0 to LS high (0 = LS low) | A |

* These parameters appear after programming the limit-switches.

| SPEED <br> OPEN. | Normal speed during opening | MOT.HZ <br> MIN to MAX | 50 Hertz |
| :--- | :--- | :--- | :--- |
| SPEED <br> CLOSE | Normal speed during closing | MOT.HZ <br> MIN to MAX | 50 Hertz |
| SPEED MX <br> CLOSE | Maximum speed during closing (Option). <br> The parameter appears after programming the P.BRAKE FE2 | MOT.HZ <br> MIN to MAX | 50 Hertz |
| OPEN. <br> SLOW | Minimum speed during opening | MOT.HZ <br> MIN to 50 Hertz | 25 Hertz |
| CLOSE <br> SLOW | Minimum speed during closing | MOT.HZ <br> MIN to 50 Hertz | 25 Hertz |
| ACCEL. <br> OPEN. | Acceleration time between start order and SPEED OPEN frequency. <br> Acceleration time between start order and SPEED OPEN frequency. | 0.1 to 9.9 secondes | 2.0 secondes |
| ACCEL. <br> CLOSE | Acceleration time between start order and SPEED CLOSE frequency. <br> Valid only for the closing direction. | 0.1 to 9.9 secondes | 2.0 secondes |
| TEMPOR. <br> OPENING | Delay time between the opening braking point and the SLOW OPEN frequency. <br> Valid only for the opening direction. | 0.1 to 9.9 secondes | 2.0 secondes |
| TEMPOR. <br> CLOSE | Delay time between the closing braking point and the SLOW CLOSE frequency. <br> Valid only for the closing direction. | 0.1 to 9.9 secondes | 2.0 secondes |
| ACCEL. MX | Acceleration time between start command and SPEED MX CLOSE frequency. <br> Valid only for the closing direction. <br> The parameter appears after programming the P.BRAKE FE2 | 0.1 to 5.0 secondes | 2.0 secondes |
| TEMPOR. MX | Delay time between the P.BRAKE FE2 and the SPEED CLOSE frequency. <br> Valid only for the closing direction. <br> The parameter appears after programming the P.BRAKE FE2 | 0.1 to 5.0 secondes | 2.0 secondes |


| Function | Description | Available settings | Factory settings |
| :---: | :---: | :---: | :---: |
| ACCEL. SKS | Acceleration time after direction change up to the SPEED OPEN / CLOSE frequency. <br> Valid for both directions and activation of the safety edge. | 0.1 to 1 second | 0.5 second |
| TEMPOR. SKS | Delay time after safety edge activation (SKS) and shutter stop. Valid for both directions and activation of the safety edge. | 0.1 to 1 second | 0.1 second |
| ACCEL. LB | Acceleration time after direction change up to the SPEED OPEN / CLOSE frequency. <br> Valid for both directions and cell activation. | 0.1 to 5.0 seconds | 0.5 second |
| TEMPOR. LB | Delay time after cell activation and shutter stop. Valid for both directions and cell activation. | 0.1 to 5.0 seconds | 0.5 second |
| TEMPOR. STOP | Delay time between the stop command or reaching a limit switch and stopping the shutter. <br> Valid for both directions. | 0.0 to 5.0 seconds | 0.5 second |
| RESET CONV. | Reset all parameters of the frequency converter to factory settings. | $\begin{aligned} & \text { ON } \\ & \text { OFF } \end{aligned}$ | OFF |
| OPERATOR V | Nominal operator voltage. | 100 to 500 Volts | 400 Volts |
| OPERATOR I | Nominal operator current. | 1 to 9.9 Amps |  |
| OPERATOR P | Nominal operator power. | 100 to 5000 Watts |  |
| OPERATOR PHI | Power factor (cosine Phi) of the operator | 0 to 1 |  |
| OPERATOR HZ | Nominal operator frequency | 10 to 100 Hertz | 50 Hertz |
| OPERATOR RPM | Nominal operator speed | 100 to 5000 rpm |  |
| OPERATOR HZ MIN | Minimum value to which the operator frequency can be set. | 10 to 50 Hertz | 10 Hertz |
| OPERATOR HZ MAX | Maximum value to which the operator's travel frequency can be set. | 50 to 100 Hertz | 87 Hertz |
| T BRAKE | Allows delayed brake release after a start command. Prevents the shutter from sagging when starting from an intermediate position. | 0 to 500 milliseconds | 50 milliseconds |

Comment : Compare the operator parameters with the data on the nameplate.

|  | R400 | R750 | R1250 |  |  |
| :--- | :--- | :---: | :---: | :---: | :---: |
| Function | Available settings | Factory settings |  |  |  |
| OPERATOR V | 100 to 500 Volts | 400 V |  |  |  |
| OPERATOR I | 1 to 9.9 Amps | 4.2 A | 7 A | 10 A |  |
| OPERATOR P | 100 to 5000 Watts | 1700 W | 3000 W | 4000 W |  |
| OPERATOR PH | 0 to 1 | 0.71 | 0.8 | 0.73 |  |
| OPERATOR HZ | 10 to 100 Hertz | 50 Hz |  |  |  |
| OPERATOR RPM | 100 to 5000 rpm | $1350 \mathrm{~min}^{-1}$ | $1365 \mathrm{~min}^{-1}$ | $1400 \mathrm{~min}^{-1}$ |  |


| Function | Description | Available settings | Factory settings |
| :---: | :---: | :---: | :---: |
| EXPERT MENU | Enabling or disabling the Expert setting. <br> Factory setting (OFF) = Limited number of parameter settings displayed in <br> INPUT mode : <br> - Menu Language <br> - P.INT. OPEN <br> - OPENING TIME <br> - WARNING <br> - CLOSED. FAST <br> - REVERSE OFF <br> - INPUT 1 <br> - AUTOHOLD <br> - P.BRAKE OPEN <br> - P.BRAKE CLOSED <br> - SPEED OPEN <br> - SPEED CLOSE <br> - OPEN. SLOW <br> - CLOSE SLOW. <br> - ACCEL. OPEN. <br> - ACCEL. CLOSE. <br> - TEMPOR. OPEN. <br> - TEMPOR. CLOSE. <br> - OPERATOR V <br> - OPERATOR I <br> - OPERATOR P <br> - OPERATOR PHI <br> - OPERATOR HZ <br> - OPERATOR RPM <br> - EXPERT MENU <br> If this parameter is set to ON, it will be possible to consult and modify all the parameters of the INPUT mode. | $\begin{aligned} & \text { ON } \\ & \text { OFF } \end{aligned}$ | OFF |
| $\begin{aligned} & \text { BOOST } \\ & \text { CONT. } \end{aligned}$ | Constant increase of the voltage as a function of the output frequency. At low output frequencies, the effective ohmic resistances of the winding must not be neglected in order to maintain the operator flux. In order to balance possible losses, maintain the load and magnetization ; It is possible to increase the inverter output voltage through this parameter. | 0 to 250 Volts | 50 Volts |
| $\begin{aligned} & \text { BOOST } \\ & \text { ACCEL } \end{aligned}$ | Causes an increase in voltage during acceleration/deceleration and generates additional torque during each acceleration and braking procedure. | 0 to 250 Volts | 50 Volts |
| $\begin{aligned} & \text { BOOST } \\ & \text { START } \end{aligned}$ | Voltage rise on start-up. Useful for starting a load. Active after the 1st acceleration procedure, after a run command. <br> Setting too high a starting increase (BOOST START) acts on the converter, which limits the current intensity, the output frequency is then limited to a value lower than the nominal frequency. | 0 to 250 Volts | 0 Volt |

Explanation of relay modes: $\square$ not used.
1 -Light functions :

| MOD | Name | Bottom limit-switch | Top limit-switch | Startup Warning | During door movement |
| :---: | :---: | :---: | :---: | :---: | :---: |
| MOD1 | Red light $1^{* * *}$ | On/Off * | Off ** | Flashing | On |
| MOD2 | Red light 2 *** | On/Off * | Off ** | Flashing | Flashing |
| MOD3 | Red light $3^{* * *}$ | On/Off * | Off ** | On | On |
| MOD18 | Red light 4 *** | Off | Off | Flashing | Off |
| MOD23 | Green light *** | Off | On ** | Off | Off |
| MOD60 | Red light 1 **** | On/Off * | Off ** | Flashing | On |
| MOD61 | Red light 2 **** | On/Off * | Off ** | Flashing | Flashing |
| MOD62 | Green light **** | Off | On ** | Off | Off |

* According to parameter LIGHTS STANDBY.
** If 2-way traffic control is activated : Depends on whether it's open inside or outside.
*** If 2-way traffic control is activated: Interior light.
**** If 2-way traffic control is enabled : Exterior light.


## 2 - Position messages :

| MOD | Name |  |
| :--- | :--- | :--- |
| MOD6 | Top limit-switch | The relay closes the contact, if the shutter is in the upper end position |
| MOD7 | Bottom limit-switch | The relay closes the contact, if the shutter is in the bottom limit-switch position |
| MOD8 | Top limit-switch position | The relay closes the contact, if the shutter is not in the upper limit-switch position |
| MOD9 | Bottom limit-switch position | The relay closes the contact, if the shutter is not in the bottom limit-switch position |
| MOD10 | Partial opening position | The relay closes the contact if the shutter is in the partially open position |
| MOD11 | Partial closure position | The relay closes the contact, if the shutter is in the partially closed position |
| MOD12 | Partial closing position up to <br> the bottom limit-switch | lhe relay closes the contact, if the shutter is between the partial closing position and the bottom <br> limit-switch |
| MOD19 | Partial opening position up <br> to top limit-switch | The relay closes the contact, if the shutter is between the partial open position and the upper limit <br> switch |

## 3 - Pulse signals :

| MOD | Name | Comments |
| :--- | :--- | :--- |
| MOD4 | Pulse in order to open <br> from the inside | The relay closes the contact for 1 second, if the shutter receives an open command from the inside. <br> With this pulse, it is possible to control the light, for example. |
| MOD27 | Pulse after having reached <br> the limit-switch | The relay closes the contact for 2 seconds, when the shutter reaches the top limit-switch. <br> With this pulse, it is possible to open the next partition, for example. |
| MOD40 | Pulse in order to open <br> from the outside | The relay closes the contact for 1 second if the shutter receives an open command from outside. <br> With this pulse, it is possible to control the light, for example. |

4 - Brake functions (only adjustable on relay) :

| MOD | Name | Comments |
| :--- | :--- | :--- |
| MOD14 | Brake (quiescent current <br> principle) | The brake rectifier switch is controlled by the relay to ensure quicker functioning of the brake. <br> The contact is closed and the brake is therefore released as soon as the shutter moves (quiescent <br> current principle). |
| MOD15 | Brake (working current prin- <br> ciple) | The brake rectifier switch is controlled by the relay to ensure quicker functioning of the brake. <br> The contact is open and the brake is therefore released as soon as the shutter moves (operating <br> current principle). |
| MOD16 | Brake (quiescent current <br> principle) activated at high <br> end position | The brake rectifier switch is controlled by the relay to ensure quicker functioning of the brake. <br> The contact is closed and the brake is therefore released as soon as the shutter moves <br> (quiescent current principle). <br> So that the shutter stops smoothly at the upper limit-switch, the contactor is not switched in the top <br> limit-switch position (opening time). |

## 5 - Error messages :

| MOD | Name |  |
| :--- | :--- | :--- |
| MOD5 | Fault signal | Comments |
| MOD17 | Safety edge activated | Thl the errors in the chapter 'display of faults and solutions' will activate the relay. |
| Ahe fault with opens the safety edge or a fail test is displayed from MOD5. |  |  |.

## 6 - Motion signal :

| MOD | Name | Comments |
| :--- | :--- | :--- |
| MOD29 | The shutter opens | Activated when moving to open. |
| MOD30 | The shutter is closing | Activated during closing movement. |
| MOD43 | The shutter opens <br> and closes | Activated with every move. |

## 7 - Functions for external accessories :

| MOD | Name | Comments |
| :---: | :---: | :---: |
| MOD13 | Magnetic latch function | The relay closes before each movement of the shutter. The relay is open in the standby position. A delay time of 0.5 seconds is set before each shutter movement. |
| MOD21 | Anti-lift safety device test | The relay produces a test signal once the bottom limit-switch has been reached and it waits until the stop circuit is activated in response to the test signal. |
| MOD22 | Activation of radio transmission system 1 and 4 Testing of light curtain 1 | The relay produces a test signal once the top limit-switch has been reached and it waits until the safety edge input is activated in response to the test signal. |
| MOD24 | Condenser activation | For each move command, the relay is closed for roughly 1 second. <br> Using this relay, a starter condenser required for an alternative current is activated to ensure the operator starts up safely. |
| MOD25 | Outside lighting function | For each open command, the relay is closed for 2 minutes and it is therefore possible to use it to control the lighting. |
| MOD26 | Radio 2 and 4 transmission system activation | Before each close command, the radio transmission system is activated with a pulse. The activation time must be set in the transmission system. The activation of the system enables delayed closing of roughly 0.5 seconds. |
| MOD28 | Relay disabled | The relay is usually deactivated, the contact is always open. |
| MOD36 | Pneumatic cylinder for wicket door locking (thresholdfree door system) | At each opening command, the relay is activated and accosts a pneumatic cylinder which mechanically locks the wicket door. The locking position of the cylinder is consulted on a limit switch. Only after this switch is activated does the door start moving. The relay remains active until the last point is reached. |
| MOD37 | Test of the stop signal on radio transmission system 1 and 3 | The relay produces a test signal once the top limit-switch has been reached and it waits until the stop circuit is activated in response to the test signal. |
| MOD38 | Testing of light curtain 2 (8,2 $\mathrm{k} \Omega$ ), connection to input 2 (X4 between 11 and 12) | The relay produces a test signal once the top limit-switch has been reached and it waits an interruption from input 2 in response to the test signal. |
| MOD41 | Radio transmission system activation in opening direction | The relay produces a test signal once the bottom limit-switch has been reached and it waits for an interruption from input 2 as a response to the test signal. |

## 8 - Input-dependent messages :

| MOD | Name | Comments |
| :--- | :--- | :--- |
| MOD32 | Battery operation | Activated during battery operation. Input 2 is bridged (setting MOD5). |
| MOD33 | No battery operation | Activated when mains power is supplied. Input 2 is open (setting MOD5). |
| MOD34 | BMA signal | Switches on when a fire detector is activated. <br> Follows the signal from input 1, in case of MOD 5 to 9 and 13 settings. <br> In this case, input 1 is supplied with a signal from the fire detector box, and opens or closes <br> the shutter to the end position or partial position, depending on the settings. |

Explanations of inputs : MOD not used.
1 - Functions of input 1 :

| MOD | Name | Comments |
| :---: | :---: | :---: |
| MOD1 | Partial open button | By pressing the button (input 1), the shutter opens to the partial opening position. |
| MOD2 | Partial opening switch | Closed : All opening orders go to the partial open position. Open : All opening commands go to the high limit-switch. |
| MOD3 | Automatic closing switch | Closed : No automatic closing (stop opening time). Open : Automatic closing activated (if open time >0). |
| MOD4 | External time (continuous opening) | The door opens as soon as the contact closes and stays in the open position (opening time stopped) until the contact opens. <br> This is followed by automatic closing (if opening time $>0$ ). <br> This function can be interrupted by pressing the close button. <br> The door closes. |
| MOD5 | Switch BMA 3 (partial opening) NO | Control function in case of activated fire detector. <br> Open : Normal function. <br> Closed : Partial opening of the shutter. The position of the partial opening is approached from both directions, regardless of the current shutter position. <br> BUTTON : No function. <br> LS / SKS : The shutter stops and moves freely (when closed), closing again after 5 seconds. STOP: Interruption of the emergency shutdown for the duration of the action. |
| MOD6 | Switch BMA 1 <br> (emergency closing) NO | Control function in case of activated fire detector. <br> Open : Normal function. <br> Closed: Emergency closing of the shutter. <br> BUTTON : No function. <br> LS / SKS : The shutter stops and moves freely, new emergency closing after 5 seconds. STOP: Interruption of the emergency closing for the duration of the action. |
| MOD7 | Switch BMA 1 <br> (emergency closing) NO | Control function in case of activated fire detector. <br> Closed : Normal function. <br> Open : Emergency closing of the shutter. <br> BUTTON : No function. <br> LS / SKS : The shutter stops and moves freely, new emergency closing after 5 seconds. STOP: Interruption of the emergency closing for the duration of the action. |
| MOD8 | Switch BMA 2 <br> (emergency opening) NO | Control function in case of activated fire detector. <br> Open : Normal function. <br> Closed : Emergency opening of the shutter. <br> BUTTON : No function. <br> LS / SKS : No function. <br> STOP: Interruption of the emergency opening for the duration of the action. No automatic shutdown after the BMA signal is turned off. |
| MOD9 | BMA 2 switch (emergency opening) NO | Control function in case of activated fire detector. <br> Closed : Normal function. <br> Open: Emergency opening of the shutter. <br> BUTTON : No function. <br> LS / SKS : No function. <br> STOP: Interruption of the emergency opening for the duration of the action. No automatic shutdown after the BMA signal is turned off. |


| MOD | Name |  |
| :--- | :--- | :--- |
| MOD10 | $\begin{array}{l}\text { Ventilation knob NO } \\ \text { (partial closing) }\end{array}$ | $\begin{array}{l}\text { Partial opening of the curtain. By actuating an additional button on input 1, the shutter moves to } \\ \text { the partial closing position from both directions, independently of the current shutter position. }\end{array}$ |
| MOD11 | Automatic close button | $\begin{array}{l}\text { 1st actuation : No automatic closing, the opening time is stopped } \\ \text { 2nd actuation : Automatic closing activated (if opening time > 0) } \\ \text { 3rd actuation : No automatic closing, the opening time is stopped } \\ \ldots\end{array}$ |
| MOD12 | $\begin{array}{l}\text { Laser scanner } \\ \text { (height recognition) }\end{array}$ | $\begin{array}{l}\text { In combination with input 2 (MOD6). } \\ \text { See explanations on entry 2. }\end{array}$ |
| MOD13 | $\begin{array}{l}\text { Switch BMA 3 } \\ \text { (partial opening) NO }\end{array}$ | $\begin{array}{l}\text { Control function in case of activated fire detector. } \\ \text { Closed : Normal function. } \\ \text { Open : Partial opening of the shutter. The position of the partial opening is approached from } \\ \text { both directions, regardless of the current shutter position. }\end{array}$ |
| BUTTON : No function. |  |  |
| LS / SKS : The curtain stops and moves freely (when closed), closing again after 5 seconds. |  |  |
| STOP : Interruption of the emergency shutdown for the duration of the action. |  |  |$\}$

## 2 - Input 2 functions :

| MOD | Name |  |
| :--- | :--- | :--- |
| OFF |  | Not active |
| MOD2 | Wicket door interrupter $(8.2 \mathrm{k} \Omega)$ | Generally active. Stop in case of discrepancies. |
| MOD3 | Safety edge opening $(8.2 \mathrm{k} \Omega)$ | $\begin{array}{l}\text { Safety edge active in opening. } \\ \text { Stopping and reversing to the low limit switch by activating the safety edge. }\end{array}$ |
| MOD4 | Safety edge opening (8.2k $\Omega)$ | $\begin{array}{l}\text { Safety edge active in opening. } \\ \text { Stopping reversing } 2 \text { seconds by activating the safety edge. }\end{array}$ |
| MOD5 | $\begin{array}{l}\text { Battery operation } \\ \text { (special MDFU) NO }\end{array}$ | $\begin{array}{l}\text { Activated when battery power is supplied. } \\ \text { Switching relay MOD32/MOD33. }\end{array}$ |
| MOD6 | $\begin{array}{l}\text { Radar motion detector } \\ \text { (height recognition) NO }\end{array}$ | $\begin{array}{l}\text { The function is connected to input 1 (MOD12 - Laser scanner). The preceding laser scanner } \\ \text { identifies the height of the vehicle. The connected radar generates an opening command upon } \\ \text { activation. } \\ \text { - The laser scanner identifies high vehicles (e.g. trucks) and switches input 1 (MOD12) to ON. } \\ \text { The radar registers the vehicle and triggers the movement of the shutter. } \\ \text { The shutter is set in motion to reach the top limit-switch. } \\ \text { - The laser scanner identifies low vehicles (e.g. cars) and switches input } 1 \text { (MOD12) to OFF. } \\ \text { The radar registers the vehicle and triggers the movement of the shutter. } \\ \text { The shutter is set in motion to reach the partial opening. }\end{array}$ |
| All other opening orders (on X3, X7, X9 and X13) bring the shutter to the high limit switch. |  |  |
| The function of input 1 (MOD12) is then irrelevant. |  |  |$]$


| MOD | Name | Comments |
| :--- | :--- | :--- |
| MOD7 | Light curtain 2 (PNP) | Identical behavior as light curtain 1 (SKS MOD 4 to 6) <br> - Light strip active in opening. <br> - Stop and reversal when the light curtain is activated. <br> The inversion mode (inversion/release) is adopted. |

## Diagnosis mode / Error memory :

| Display | Meaning | Status |
| :---: | :---: | :---: |
| TOP LS | Top limit-switch | OFF : The top limit switch is reached ON: The top limit switch is not reached |
| BOT LS | Bottom limit switch | OFF : Bottom limit switch is reached <br> ON : Bottom limit switch is not reached |
| OPEN BUTTON | Box key / Open input | ON: Button is pressed / Input is active <br> OFF : Button is not pressed / Input is not active |
| CLOSE <br> BUTTON | Box key / Closing input | ON: Button is pressed / Input is active <br> OFF : Button is not pressed / Input is not active |
| INPUT 1 | INPUT 1 (X4 between 9 and 10) | ON : Input 1 is active <br> OFF : Input 1 is not active |
| INPUT 2 | INPUT 2 (X4 between 11 and 12) | ON : Input 2 is active <br> OFF : Input 2 is not active <br> -: Not activated |
| SKS | Safety edge 1 <br> (DW, $8.2 \mathrm{k} \Omega$ or Opto Sensor) | ON: The system is closed <br> OFF : The system has stopped (fault) |
| SKS 3 | Safety edge 3 <br> ( $8.2 \mathrm{k} \Omega$ or opto-sensor) | ON : The system is closed <br> OFF : The system has stopped (fault) <br> -: Not activated |
| SKS 4 | Safety edge 4 <br> ( $8.2 \mathrm{k} \Omega$ or opto-sensor) | ON: The system is closed <br> OFF : The system has stopped (fault) <br> - : Not activated |
| PULSE | Box key / Pulse <br> (X3 between 7 and 8) | ON: Button is pressed / Input is active <br> OFF : Button is not pressed / Input is not active |
| TIMER | Weekly timer (plug-in) | ON : The timer is active <br> OFF : The timer is not active |
| PHOTO CELL. | Flow cells 1 (X4 between 1 and 4) | ON : The cell signal is correct <br> OFF : Interrupted light beam or defective cells |
| PHOTO CELL. $\text { \| } 2$ | Flow cells 2 <br> Connection to input 1 (X4 between 9 and 10) | ON : The cell signal is correct <br> OFF : Interrupted light beam or defective cells |
| REAR CHAIN | Safety circuit 1 <br> Shutter emergency stop system | ON: The safety circuit is closed <br> OFF : The safety circuit is interrupted |
| STOP | Stop button (on the front panel) | ON : The button is not pressed <br> OFF : The button is pressed |
| CM ROT | Direction of rotating field | RIGHT: Setting for a right-rotating field <br> LEFT : Setting for a left-rotating field |
| CYCLE | Counter for number of shutter cycles | Display of the current shutter cycles ( 1 Cycle $=1$ Open +1 Close) Calculations are made when the upper and lower limit-switches are reached. |
| SERVICE | Operation of the service alarm Setting to SERVICE parameter and PN 2 code | OFF : Maintenance display inactive <br> 0 à 99999 : The maintenance display is active Display of the remaining shutter cycles before the maintenance message. |
| AWG <br> (ENCODER) | Absolute value encoder position indication | Shutter position value display |
| CYCLE <br> NUMBER <br> ERROR | The error memory of the case can be consulted with information on frequency and cycles. <br> The list of error messages can be scrolled using the + and - buttons on the LCD display. See chapter: Display of faults and solutions. <br> Deleting the error memory : <br> To activate the INPUT, press the + and - buttons for $\approx 2$ seconds. Each error message must be deleted one by one. | The display changes every 2 seconds from : <br> - The qualification of the error, <br> - To the frequency of the problem <br> - And which cycle the error occurred last time. <br> The list shows errors that have already occurred. |

## Fault display and solutions

## LCD screen fault display :

$\square$ not used.

| Fault / Message | Cause | Solution |
| :---: | :---: | :---: |
| The system does not react. | - Power is off. | - Check the power supply to the operator and the box. |
| After pressing the open button, the shutter moves to the low limit switch. After pressing the close button, the shutter moves to the upper limit switch. | - The direction of the rotating field is incorrect. | - Reverse the direction of the rotating field. |
| FAULT - X | - Internal software or hardware error. | - Restart the box. |
| REAR CHAIN | - The stop circuit is interrupted. <br> X3 between 1 and 2 : Emergency stop, electric anti-slack cable breaker. <br> X6 between 1 and 2 : Internal on/off. <br> X11 between 4 and 8 : AWG drive safety circuit. <br> X14 between 4 and 8 : RS485 interface. <br> X2 between B1 and B2 : MEC drive safety circuit. <br> X3 between 3 and 4 : External stop button. <br> X7 between 1 and 2 : Internal stop button. | - Check the safety circuit, locate the interruption and solve the problem. |
| ERR DURATION MVT | - The programmed movement time has been exceeded. | - Check the shutter path and the duration of the movement. <br> - Reprogram the movement time if necessary. |
| ERR AWG | - The signal transmission between the encoder and the control box is interrupted or faulty. | - Check the cable/plug connections and change them if necessary. |
| ERR END OF COUR. | - The shutter is outside the programmed limit switches. <br> - The limit-switches have not yet been programmed. | - Switch the box off and on again using the front disconnecting switch. <br> - Reprogram the limit-switches. |
| ERR FORCE | - Force control is engaged. | - Check that the shutter is not mechanically obstructed. |
| OS ROTARY FAULT | - The direction of the rotating field is incorrect. | - Check the rotating field and change it if necessary, see chapter : Adjusting the limit switches (Reversing the direction of rotation). |
| ERR SKS CLOSE | - Safety edge 1 is not operating correctly when closing (X4 between 5 and 8) | - Check the safety edge and the coiled cable. |
| ERR SKS OPEN 2 | Safety edge 2 does not work correctly when opening (X4 between 11 and 12) input 2 | - Check the safety edge and the coiled cable. |
| STOP ERROR 2 | Safety circuit 2 is interrupted. Wicket door switch $8.2 \mathrm{k} \Omega$ (X4 between 11 and 12) input 2. | - Check wicket door switch. |
| ERR SKS CLOSE 3 | The safety edge 3 is not operating correctly when closing (X20). Pluggable radio transmission system Radio channel 1. | Check the safety edge. <br> - Check the Radio transmission system if necessary. |
| ERR SKS OPEN 3 | - The safety edge 3 is not operating correctly when opening (X20). Pluggable radio transmission system Radio channel 1. | Check the safety edge. <br> - Check the Radio transmission system if necessary. |
| STOP ERROR 3 | Safety circuit 3 is interrupted. (X20) Plug-in transmission system Radio channel 1. | Check the safety circuit. <br> - Check the Radio transmission system if necessary. |
| ERR SKS CLOSE 4 | The safety edge 4 is not operating correctly when closing (X20). Système de transmission enfichable Radio canal 2. | Check the safety edge. <br> - Check the Radio transmission system if necessary. |
| ERR SKS OPEN 4 | - The safety edge 4 is not operating correctly when opening (X20). Pluggable Radio Channel 2 transmission system. | Check the safety edge. <br> - Check the Radio transmission system if necessary. |
| STOP ERROR 4 | Safety circuit 4 is interrupted (X20). Plug-in transmission system Radio channel 2. | Check the safety circuit. <br> - Check the Radio transmission system if necessary. |


| Fault / Message | Cause | Solution |
| :---: | :---: | :---: |
| ERR T SKS | -The connected pneumatic safety edge test was not successful. <br> - Test of radio transmission system 1 to 4, failed. | - Check the DW switch, the coiled cable and the rubber profile. <br> - Check the POINT DW setting. <br> - Check the radio transmission system. <br> - Check the MOD relay set for the transmission system, see chapter: <br> 7 - Functions for external accessories. |
| ERR PHOTO/C | - The connected cell has a permanent failure (X4 between 1 and 4) | - Check the cell (operation/direction). <br> - Check the wiring. |
| ERR PHOTO/C 2 | The connected cell has a permanent failure ( X 4 between 9 and 10 ) input 1. | Check the cell (operation/direction) Check the wiring. |
| P/C SHOCK ERR | - The bifilar cell test failed. | Check the cell (operation/direction) Check the wiring. |
| STOP TEST ERROR | The wicket door switch test ( $8.2 \mathrm{k} \Omega$ ) failed. Input 2. | - Check wicket door switch. |
| ANTI-LIFT ERR | - The anti-lift test failed. Relay MOD21. | Check the cell (operation/direction). <br> Check the wiring. |
| CYLINDER ERROR | - The limit switch for wicket door locking without threshold has not been activated within 10 seconds after the opening command. | - Check the cylinder limit switch. |
| ERR MSBUS | The communication between the box and the connected MS-BUS module is interrupted. | Check the cable/plug connections and change them if necessary. |
| ERR CONVERT. | Communication error. <br> - The communication between the frequency converter and the box is disturbed. <br> - The bridge (F) between DIC and OV is absent. | - Check the communication line (C), the connections to the box on the frequency converter. <br> - Place the bridge (F) between DIC and OV (if frequency converter type V20). <br> - Confirm with STOP. |
| ERR CONVERT. 1 | Overcurrent. <br> - The power of the operator does not match the power of the converter. <br> - Short circuit in the operator cable. <br> - Earth fault. | - Check the operator/converter power. <br> - Check operator/operator cable for short circuit or earth fault. <br> - Compare the set operator parameters with the data on the nameplate. <br> - Check the ease of operation of the shutter. <br> - Confirm with STOP. |
| ERR CONVERT. 2 | Power surge. <br> - Mains voltage too high. <br> - The operator runs in generator mode for too quick a stop or an active load that drives the operator. | - Check the power supply to the operator and the box. <br> - Confirm with STOP. |
| ERR CONVERT. 3 | Undervoltage. <br> - Mains voltage too low. <br> - Loss of mains voltage. | - Check the power supply to the operator and the box. <br> - Check the strength of all connections. <br> - Confirm with STOP. |
| ERR CONVERT. 4 | Converter superheat. <br> - Converter overload. <br> - Ambient temperature too high. | - Check the operator/converter power. <br> - Compare the set operator parameters with the data on the nameplate. <br> - Check the running time. <br> - Check the ease of operation of the shutter. <br> - Confirm with STOP. |
| ERR CONVERT. 5 | I2T converter. <br> - Converter overload. <br> - The power of the operator does not match the power of the converter. <br> - Stress cycle too high. | - Check the operator/converter power. <br> - Compare the set operator parameters with the data on the nameplate. <br> - Check the stress cycle. |
| ERR CONVERT. 11 | Operator overheating I2.T. <br> - Operator overload. | - Check the ease of operation of the shutter. <br> - Confirm with STOP. |
| ERR CONVERT. 51 | Internal error. | - Contact the after-sales service. |
| ERR CONVERT. 52 | Internal error. | - Contact the after-sales service. |
| ERR CONVERT. 60 | Internal error. | - Contact the after-sales service. |
| ERR CONVERT. 72 | Internal error. | - Contact the after-sales service. |
| ERR CONVERT. 85 | Internal error. <br> - External error for a command via the terminals. | - Check the connection terminals on the converter (communication line D). <br> - Confirm with STOP. |

In the event of other faults / fault messages, please contact customer service.

Please note : After having solved the cause of the failure, the box must be switched off and restarted in the case of the following errors (menu INPUT $\rightarrow$ parameter RESTART $\rightarrow$ ON) :

- OS ROTARY FAULT
- ERR DURATION MVT
- ERR END OF COUR.


## LED fault display :

- LED H4 (green, base plate)

| Fault / Message | LED display | Comments |
| :--- | :--- | :--- |
| No operating voltage | Off | No supply voltage available |

- LED H6 (rouge, platine-support)

| Fault / Message | LED display | Comments |
| :---: | :---: | :---: |
| REAR CHAIN | 1 flashing | The stop chain must be closed. <br> - Check the safety circuit, locate the interruption and resolve the problem. |
| ERR AWG | 2 flashing | The signal transmission between the encoder and the box is interrupted or faulty. <br> - Check the cable/plug connections and change them if necessary. |
| ERR END OF COUR. | 3 flashing | The shutter is outside the programmed limit switches or they are not yet programmed. <br> - Switch the box off and on again using the front disconnecting switch. <br> - Program the limit-switches. |
| OS ROTARY FAULT | 4 flashing | - The rotating field is incorrect. <br> - Check the rotation field and modify if necessary, see chapter : Adjusting the limit switches (Reversing the direction of rotation). |
| ERR FORCE | 5 flashing | The force control is activated. <br> - Check that the shutter is not mechanically obstructed. |
| ERR DURATION MVT | 6 flashing | - The programmed movement time has been exceeded. <br> - Check the shutter path and the duration of the movement. <br> - Reprogram the movement time. |
| ERR CONVERT. | 7 flashing | - The communication between the frequency converter and the box is interrupted or disturbed. <br> - Check data cable (D) and connections. <br> - Confirm with STOP. |
| ERR MSBUS | 9 flashing | - Communication error between the box and the connected MS-BUS terminal. <br> - Check the cable/plug connections and change them if necessary. |
| ERR SKS | Permanent light Operation by hold-to-run only. | Safety edge faulty in opening or closing. <br> - Check the safety edge and the spiral cable, and check the radio transmission system if necessary. |
| ERR PHOTO/C | Permanent light Operation by hold-to-run only in closing. | - The connected cell has a permanent failure. <br> - Check the cell (operation/orientation). <br> - Check the wiring. |

## In case of operator malfunction

## Most importantly, never put the operator into continuous operation by directly activating the power contactors

## Triple-phase operator: Check the 400 V voltage between each phase.

 Check the 230 V voltage between phase and neutral.Check that the emergency operation control is not activated.

Lomen
=Mounting the winch on R400 operator (option)

- To fix the hoist in place, it is essential to use the 4 screws provided with the hoist (Length = $\mathbf{3 5} \mathbf{~ m m}$ ) instead of the 4 original screws (Length = 35 mm ).
Do not use an electric screwdriver to tighten the screws, as this might damage the operator.


- To fix the hoist in place, it is essential to use the 4 screws provided with the hoist (Length = 50 mm ) instead of the 4 original screws (Length = 35 mm ).
Do not use an electric screwdriver to tighten the screws, as this might damage the operator.



## to detach and display next to the fence element Emergency operation by winch (option)



1- Insert the crank into the operator as far as the stop (the operator power supply is cut off and the door cannot operate electrically).

2- Turn the crank in one direction to open the door and in the other direction to close it.
3- Once repairs are completed, remove the crank (the operator power is reactivated and the door can operate electronically).

Never pull the operator brake when repairing the operator or when it is in operation.

## Technical assistance contact

| (Installer's stamp) |
| :---: |
|  |
|  |
|  |



1- Pull the red handle as far as it will go.
(the operator power is cut off and the door cannot operate electrically).
2- Pull the safety chain in one direction to open the door and in the other direction to close it.

## Locking :

1- Pull the green handle as far as it will go.
(the operator power is reactivated and the door can operate electrically).

